DM

Stepper Motor Driver

DM856

MicroSteps Setting:400~25600 DC: 24~80V



Overview

- 8 channels output phase current setting
- Offline command input terminal
- High start speed
- High hording torque under high speed
- High performance, low price
- Opto-isolated signal I/O
- Overvoltage, under voltage, overcorrect, phase short circuit protection
- 15 channels subdivision and automatic idle-current reduction
- Motor torque is related with speed, but not related with step/revolution

The connection between the driver and the two-phase hybrid stepping motor is four-wire. The motor windings are connected in parallel and in series, and the connection method is good. The high-speed performance is good, but the driver current is large (1.73 times the motor winding current). The drive current is equal to the motor winding current.

	Features				
	Input voltage	24~80V DC			
	Output current	2.1A~5.6A			
	Input current	<4A			
D	Humidity	Not condensation, no water droplets			
\sqrt{I}	Using environment	-10 ~ 45 °C, avoid dust and corrosive gas			
	Storage environment	-40~+70°C			
	Weight	200g			

Control Signal			
Symbol	Name		
PUL+	Pulse signal +		
PUL-	Pulse signal -		
DIR+	Direction signal+		
DIR-	Direction signal-		
ENBL+	Enable signal +		
ENBL-	Enable signal -		

When the offline enable signal is active, the drive fave is est, any valid pulses are disabled, the output power component off, and the motor has no holding torque

Moto and power					
Symbol	N ne)	Remark			
Α+	se A+				
A-	Phase A-				
B+	Phase B+				
B-	Phase B-				
DC+	Input Power +	+24~80V			
DC-	Input Power-	0V			

DIP switch setting

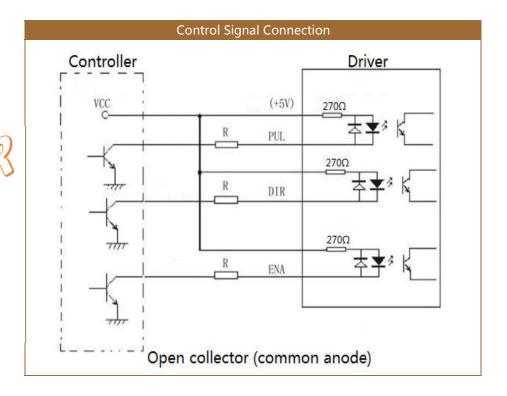
In order to drive stepping motors with different torques, the user can set the output phase current (effective value) of the driver by the DIP switches SW1, SW2 and SW3 on the driver panel. The output current corresponding to each switch position, different models of drivers The corresponding output current values are different. See the table below for details.

SW1	SW2	SW3	PEAK (A)	RMS (A)
OFF	OFF	OFF	Def	ault
ON	OFF	OFF	2.1	
OFF	ON	OFF	2.7	1.
ON	ON	OFF	3.2	2.3
OFF	OFF	ON	V8/ C	2.7
ON	OFF	ON	4.7	3.1
OFF	ON	ON	4.9	3.5
ON	ON	V pl 🔼	5.6	4

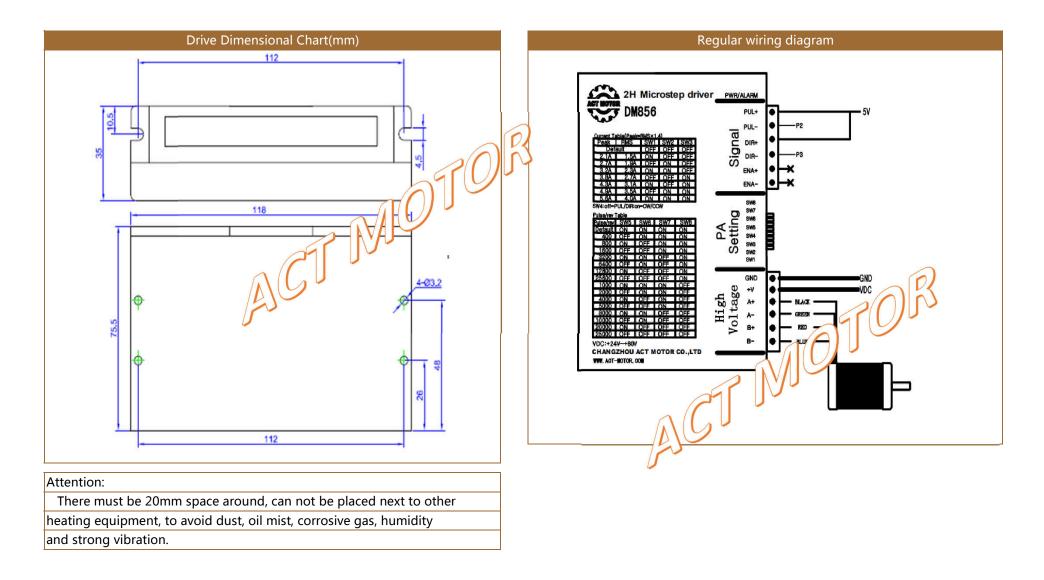
SW4: 'OFF' has no semi-flow unction; 'ON' has semi-flow function.

The semi-flow function means that after 500ms without stepping pulse, the output current of the driver is automatically reduced to 70% of the rated output current to prevent the motor from heating.

MicroSteps Setting								
RPM	400	800	1600	3200	6400	12800	25600	/
SW5	OFF	ON	OFF	ON	OFF	ON	OFF	/
SW6	ON	OFF	OFF	ON	ON	OFF	OFF	/
SW7	ON	ON	ON	OFF	OFF	OFF	OFF	/
SW8	ON	ON	ON	ON	ON	ON	ON	/
RPM	1000	2000	4000	5000	8000	10000	20000	25000
SW5	ON	OFF	ON	OFF	ON	OFF	ON	OFF
SW6	ON	ON	OFF	OFF	ON	ON	OFF	OFF
SW7	ON	ON	ON	ON	OFF	OFF	OFF	OFF
SW8	OFF	OFF	OFF	OFF	OFF	OFF	OFF	OFF



	Status light
PWR	Green light, bright when working
PWR	Lights off, lights up when fault occurs, motor phase-to-phases or
PVVK	circuit, overvoltage protection and undervoltage project on
	ACT



Adjustment of troubleshooting					
Alarm indicator	Reasons	Measures			
LED off turn	Wrong connection for power	Check wiring of power			
LED OII tuili	Low-voltages for power	Enlarge voltage of power			
Motor doesn't run, without	Wrong connection of stepper motor	Correct its wiring			
holding torque	RESET signal is effective when offline	Make RESET ineffective			
Motor doesn't run, but maintains	NA/ith autimout mulas sismal	A disease DNANA Os aisses al lascal			
holding torque	Without input pulse signal	Adjust PMW & signal level			
Mater runs urena direction	Wrong wires' connection	Change connection for any of 2 wires			
Motor runs wrong direction	Wrong input direction signal	Change direction setting			
Matar's halding targue is	Too small relative to current setting	orrect rated current setting			
Motor's holding torque is	Acceleration is too fast	Reduce the acceleration			
Matautaunus ia ta a anall	Motor stalls	Rule out mechanical failure			
Motor torque is too small	Driver does not match with the or	Change a suitable driver			
	ACTMO				